



An Introduction to Spinor Differential and Integral Calculus from q -Lorentzian Algebra

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Abstract. In this paper we introduce the differential and integral calculus from q -Lorentzian algebra. We establish the q -spinorial variables, the q -differential calculus and the q -complex spinorial integrals. We also define the q -spinor differential equation and the q -Lorentzian spinor differential equation. Some comments are presented at the end of the paper.

Keywords: q -Lorentzian algebra, q -spinor derivative and integral, differential spinor equation.

MSC2010: 81Q99, 46E99, 35A24, 15A66, 16T99, 17B37.

Una Introducción al Cálculo Diferencial e Integral Espinorial a partir de la q -Álgebra Lorentziana.

Resumen. En este artículo introducimos el cálculo diferencial e integral a partir de la q -álgebra lorentziana. Establecemos las q -variables espinoriales, el q -cálculo diferencial y las q -integrales espinoriales complejas. También definimos la q -ecuación diferencial espinorial y la q -ecuación diferencial espinorial lorentziana. En el final del artículo se presentan algunos comentarios.

Palabras clave: q -álgebra Lorentziana, q -derivada e integral espinorial. ecuación diferencial espinorial.

1. Introduction

Based on the work of Beretetskii et al., Lachieze-Rey, Gori et al., and Cartan, the spinor ψ^α is defined as a magnitude components $\alpha = 1, 2$ expressed as

$$\psi^\alpha = \begin{bmatrix} \psi_1 \\ \psi_2 \end{bmatrix}$$

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and its complex conjugate $\dot{\varphi}$ in terms of the rotation matrices (see [2],[3],[5],[4] for more details). Based on the work of the aforementioned authors, there are two types of operations on spinors, which are reflections and rotations. In group theory, the set of rotations described by the matrices with complex entries is group $SU(2)$, whose generators are the Pauli matrices, described in the work of Zettili [7]. In regards to rotation matrices, Gori et al. mentioned in their work that rotation matrices originated Pauli matrices in the form of:

$$R_x(\theta) = \begin{bmatrix} \cos(\theta/2) & i \sin(\theta/2) \\ i \sin(\theta/2) & \cos(\theta/2) \end{bmatrix}, R_y(\theta) = \begin{bmatrix} \cos(\theta/2) & \sin(\theta/2) \\ \sin(\theta/2) & \cos(\theta/2) \end{bmatrix}, R_z(\theta) = \begin{bmatrix} e^{i\theta/2} & 0 \\ 0 & e^{-i\theta/2} \end{bmatrix}, \quad (1)$$

being θ the angle of rotation [4]. Beretetskii et al. defined the covariance and contravariance over the spinors by the relation $\psi'^1 = \psi_2, \psi'^2 = -\psi_1$ from the matrix

$$g_{\alpha\beta} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

and, similarly, for pointed spinors, $\psi_1 = \psi^2, \psi_2 = -\psi^1$ [3]. The same author defined bispinors as the pair $(\psi^\alpha, \varphi_{\dot{\alpha}})$, which form a broader group of Lorentz, and, with them, the scalar product is formulated as $(\psi^\alpha, \varphi_{\dot{\alpha}}) \cdot (f^\alpha, h_{\dot{\alpha}})$. The author of the reference [5] mentions algebra $Cl(3)$ as a space-time formulation generated by vectors e_μ , which form a basis for $\mathbb{R}^{1,3}$ that satisfies the relation $e_\mu \cdot e_\nu = g_{\mu\nu}$, inducing a 16-membered basis, as described below:

- 1 1 scalar,
- 2 (e_0, e_1, e_2, e_3) 4-vector,
- 3 $(e_0e_1, e_0e_2, e_0e_3, e_1e_2, e_2e_3, e_3e_1)$ 6- bivectors,
- 4 $(e_1e_2e_3, e_0e_2e_3, e_0e_1e_3, e_0e_1e_2)$ 4-trivectors,
- 5 $e_5 \equiv e_0e_1e_2e_3$ pseudoescalar.

In accordance with the previous statements, the same author described the Weyl spinors as

$$\begin{bmatrix} \psi^1 \\ \psi^2 \end{bmatrix}$$

and the Dirac spinor

$$\begin{bmatrix} \psi^\alpha \\ \varphi_{\dot{\alpha}} \end{bmatrix},$$

as defined in the work of Beretetskii et al [3].

The q -Lorentzian algebra was defined in the reference [1]. The quantum complex spinors have components ψ_1 and ψ^2 and conjugates $\varphi^{\dot{1}}$ and φ_2 . They meet the following q -relations.

$$\psi_1\psi^2 = q\psi^2\psi_1, \quad \psi^2\varphi^{\dot{1}} = q\varphi^{\dot{1}}\psi^2, \quad (2)$$

$$\psi_1\varphi^{\dot{1}} = \varphi^{\dot{1}}\psi_1 - q(q + q^{-1})^{1/2}\varphi_2\varphi^{\dot{1}}, \quad \psi^2\varphi^{\dot{1}} = \varphi^{\dot{1}}\psi^2, \quad (3)$$

$$\psi_1\varphi_2 = q\varphi_2\psi_1, \quad \varphi^{\dot{1}}\varphi_2 = q^{-1}\varphi_2\varphi^{\dot{1}}. \quad (4)$$

Definition 1.1. Considering spinors $\psi^\alpha, \varphi_{\dot{\alpha}}$ and $\{\tau^1, T^2, S^1, \sigma^2\}$ as the generators of the q -Lorentzian algebra for the group $U_q(su(2))$ [6], we have:

1. For $\psi^\alpha, \alpha = 1, 2$

$$\tau^1 \psi_1 = \psi_1 \tau^1, \tag{5}$$

$$\tau^1 \psi^2 = \psi^2 \tau^1 - q(q + q^{-1})^2 \psi_1 T^2, \tag{6}$$

$$T^2 \psi_1 = q^{-1} \psi_1 T^2, \tag{7}$$

$$S^1 \psi_1 = q \psi_1 S^1, \tag{8}$$

$$T^2 \psi^2 = q \psi^2 T^2, \tag{9}$$

$$S^1 \psi^2 = q^{-1} \psi^2 S^1 - \psi_1 \sigma^2, \tag{10}$$

$$\sigma^2 \psi_1 = \psi_1 \sigma^2, \tag{11}$$

$$\sigma^2 \psi^2 = \psi^2 \sigma^2, \tag{12}$$

2. Their complex conjugates $\varphi^{\dot{\alpha}}, \alpha = \dot{1}, \dot{2}$

$$\tau^1 \varphi^{\dot{1}} = q^{-1} \varphi^{\dot{1}} \tau^1, \tag{13}$$

$$\tau^1 \varphi_2 = q \varphi_2 \tau^1, \tag{14}$$

$$T^2 \varphi^{\dot{1}} = \varphi^{\dot{1}} T^2 + q^{-1} \varphi_2 \tau^1, \tag{15}$$

$$T^2 \varphi_2 = \varphi_2 T^2, \tag{16}$$

$$S^1 \varphi^{\dot{1}} = \varphi^{\dot{1}} S^1, \tag{17}$$

$$\sigma^2 \varphi^{\dot{1}} = q \varphi^{\dot{1}} \sigma^2 + (q + q^{-1})^2 \varphi_2 S^1, \tag{18}$$

$$\sigma^2 \varphi_2 = q \varphi_2 \sigma^2. \tag{19}$$

Deformed commutation relations for q -Lorentzian algebra are defined in the next proposition, on the quantum-symmetric plane and the quantum anti-symmetric plane.

Proposition 1.2. *Considering generator T of the set $\{\tau^1, T^2, S^1, \sigma^2\}$ for the algebra $U_q(su(2))$ and the relations 2, 3, and 4, defined in [1] and [6]. The q -Lorentzian algebra for spinors in the deformed space is defined through the following relations:*

$$T(\psi_1 \psi^2 - q \psi^2 \psi_1) = (\psi_1 \psi^2 - q \psi^2 \psi_1) T, \tag{20}$$

$$T(\psi_1 \psi^2 - q \psi^2 \psi_1) = (\psi_1 \psi^2 - q \psi^2 \psi_1) T, \tag{21}$$

$$T(\varphi^{\dot{1}} \varphi_2 + q^{-1} \varphi_2 \varphi^{\dot{1}}) = (\varphi^{\dot{1}} \varphi_2 + q^{-1} \varphi_2 \varphi^{\dot{1}}) T, \tag{22}$$

$$T(\varphi^{\dot{1}} \varphi_2 + q^{-1} \varphi_2 \varphi^{\dot{1}}) = (\varphi^{\dot{1}} \varphi_2 + q^{-1} \varphi_2 \varphi^{\dot{1}}) T. \tag{23}$$

Definition 1.3. The following matrices are the bosonic q -deformed Minkowskian Pauli spin matrices defined in the Schmidt work [6]:

$$(\sigma^+)_{\alpha\dot{\beta}} = \begin{bmatrix} 0 & 0 \\ 0 & q \end{bmatrix}, \quad (\sigma^-)_{\alpha\dot{\beta}} = \begin{bmatrix} q & 0 \\ 0 & 0 \end{bmatrix}, \tag{24}$$

$$(\sigma^3)_{\alpha\dot{\beta}} = q(q + q^{-1})^{-1/2} \begin{bmatrix} 0 & q^{1/2} \\ q^{-1/2} & 0 \end{bmatrix}, \quad (\sigma^0)_{\alpha\dot{\beta}} = (q + q^{-1})^{-1/2} \begin{bmatrix} 0 & -q^{-1/2} \\ q^{1/2} & 0 \end{bmatrix}. \tag{25}$$

Likewise, the conjugated Pauli matrices are:

$$(\bar{\sigma}^+)_{\dot{\alpha}\beta} = \begin{bmatrix} 0 & 0 \\ 0 & q^{-1} \end{bmatrix}, \quad (\bar{\sigma}^-)_{\dot{\alpha}\beta} = \begin{bmatrix} q^{-1} & 0 \\ 0 & 0 \end{bmatrix}, \tag{26}$$

$$(\bar{\sigma}^3)_{\dot{\alpha}\beta} = q(q + q^{-1})^{-1/2} \begin{bmatrix} 0 & q^{1/2} \\ q^{-1/2} & 0 \end{bmatrix}, \quad (\bar{\sigma}^0)_{\dot{\alpha}\beta} = (q + q^{-1})^{-1/2} \begin{bmatrix} 0 & q^{-1/2} \\ -q^{1/2} & 0 \end{bmatrix}. \tag{27}$$

The inverse Pauli matrices

$$(\sigma_+^{-1})_{\alpha\dot{\beta}} = \begin{bmatrix} 0 & 0 \\ 0 & q^{-1} \end{bmatrix}, \quad (\sigma_-^{-1})_{\alpha\dot{\beta}} = \begin{bmatrix} q^{-1} & 0 \\ 0 & 0 \end{bmatrix}, \quad (28)$$

$$(\sigma_3^{-1})_{\alpha\dot{\beta}} = q(q + q^{-1})^{-1/2} \begin{bmatrix} 0 & q^{1/2} \\ q^{-1/2} & 0 \end{bmatrix}, \quad (\bar{\sigma}_0^{-1})_{\alpha\dot{\beta}} = (q + q^{-1})^{-1/2} \begin{bmatrix} 0 & -q^{-1/2} \\ q^{1/2} & 0 \end{bmatrix}. \quad (29)$$

Finally

$$(\bar{\sigma}_+^{-1})_{\dot{\alpha}\beta} = \begin{bmatrix} 0 & 0 \\ 0 & q^{-1} \end{bmatrix}, \quad (\bar{\sigma}_-^{-1})_{\dot{\alpha}\beta} = \begin{bmatrix} q^{-1} & 0 \\ 0 & 0 \end{bmatrix}, \quad (30)$$

$$(\bar{\sigma}_3^{-1})_{\dot{\alpha}\beta} = q(q + q^{-1})^{-1/2} \begin{bmatrix} 0 & q^{1/2} \\ q^{-1/2} & 0 \end{bmatrix}, \quad (\bar{\sigma}_0^{-1})_{\dot{\alpha}\beta} = (q + q^{-1})^{-1/2} \begin{bmatrix} 0 & -q^{-1/2} \\ q^{1/2} & 0 \end{bmatrix}. \quad (31)$$

The purpose of this article is to define the q -Lorentzian spinor variables and q -spinor differential and integral calculus and q -differential spinor equation. The paper is organized in: section 2 where it is presented the q -spinor variables and calculus. In section 3 we present the q -differential spinor equation, and the final section with comments.

2. q -Spinor variables and calculus

Definition 2.1. The q -Lorentzian spinor variables or q -spinor variables are defined according to the expressions (2), (3), and (4) as follows:

$$u_1^2 \equiv \psi_1 \psi^2 - q \psi^2 \psi_1, \quad (32)$$

$$v^{i2} \equiv \psi^2 \varphi^i - q \varphi^i \psi^2, \quad (33)$$

$$x_{12}^i \equiv \psi_1 \varphi^i - \varphi^i \psi_1 + q(q + 1)^{-1/2} \varphi_2 \varphi^i, \quad (34)$$

$$y^{2i} \equiv \psi^2 \varphi^i - \varphi^i \psi^2, \quad (35)$$

$$z_2^i \equiv \psi_1 \varphi_2 - q^{-1} \varphi_2 \varphi^i, \quad (36)$$

$$t_{12} \equiv \psi_1 \varphi_2 - q \varphi_2 \psi_1. \quad (37)$$

Definition 2.2. We consider the set $U = \{u_1^2, v^{i2}, x_{12}^i, z_2^i, y^{2i}, t_{12}\} \subset \mathbb{C}$. A function on the q -spinor variables is defined as

$$f(U) = f(u_1^2, v^{i2}, x_{12}^i, z_2^i, y^{2i}, t_{12}).$$

Definition 2.3. Let $f, g : U \rightarrow \mathbb{C}$ be functions and $u^\beta \in U$. The following properties are satisfied on the q -spinor variables, we state some clear properties of the functions on the q -spinor variables

1. $(f + g)(u^\beta) = f(u^\beta) + g(u^\beta)$.
2. $(f \cdot g)(u^\beta) = f(u^\beta) \cdot g(u^\beta)$.
3. $(f - g)(u^\beta) = f(u^\beta) - g(u^\beta)$.
4. $\left(\frac{f}{g}\right)(u^\beta) = \frac{f(u^\beta)}{g(u^\beta)}, \quad g(u^\beta) \neq 0$.

Definition 2.4. For a function $f : U \rightarrow \mathbb{C}$ and $u^\beta \in \mathbb{C}$, the q -spinor derivative is defined as:

$$\frac{d_q f}{d_q u^\beta} = \frac{f((qu)^\beta) - qf(u^\beta)}{(qu)^\beta - qu^\beta}, \quad (38)$$

and its conjugate complex

$$\frac{d_q f}{d_q v^{\dot{\alpha}}} = \frac{f((qv)^{\dot{\alpha}}) - qf(v^{\dot{\alpha}})}{(qv)^{\dot{\alpha}} - qv^{\dot{\alpha}}}. \tag{39}$$

Proposition 2.5. Let $V \subset \mathbb{C}$ be the set conformed by q -spinor variables in the form

$$V = \left\{ u^\beta, u_\alpha, v^{\dot{\alpha}}, v_{\dot{\beta}}; \alpha, \beta = 1, 2; \dot{\alpha}, \dot{\beta} = \dot{1}, \dot{2} \right\}.$$

The q -spinor functions in complex variable $f : V \rightarrow \mathbb{C}$ can be expressed as:

$$f(u^\beta) = \sum_{n=0}^{\infty} [(\bar{\sigma}_\mu)_{\dot{\alpha}\beta} f(u^\beta)]^n, \tag{40}$$

$$f(u_\alpha) = \sum_{n=0}^{\infty} [(\sigma_\mu)_{\alpha\dot{\beta}} f(u_\alpha)]^n, \tag{41}$$

$$f(v^{\dot{\alpha}}) = \sum_{m=0}^{\infty} [(\bar{\sigma}_\mu^{-1})_{\dot{\alpha}\beta} f(v^{\dot{\alpha}})]^m, \tag{42}$$

$$f(v_{\dot{\beta}}) = \sum_{m=0}^{\infty} [(\sigma_\mu)_{\alpha\dot{\beta}} f(v_{\dot{\beta}})]^m, \tag{43}$$

$(\bar{\sigma}_\mu)_{\dot{\alpha}\beta}, (\bar{\sigma}_\mu^{-1})_{\dot{\alpha}\beta}, (\sigma_\mu)_{\alpha\dot{\beta}}, \mu = \{+, -, 3, 0\}$ being the deformed spin matrices in the Minkowski space defined in the introduction .

Theorem 2.6. Assume that $f : \mathbb{C} \rightarrow \mathbb{C}$ and $g : \mathbb{C} \rightarrow \mathbb{C}$ are spinorial differentiable functions at $u^\beta, v^{\dot{\alpha}} \in \mathbb{C}$. Then

1. the sum $g + h : \mathbb{C} \rightarrow \mathbb{C}$ is q -differentiable at u^β and

$$\frac{d_q f}{d_q u^\beta} = \frac{d_q g}{d_q u^\beta} + \frac{d_q h}{d_q u^\beta}.$$

2. the product $gh : \mathbb{C} \rightarrow \mathbb{C}$ is q -differentiable at u^β and

$$\frac{d_q f}{d_q u^\beta} = g[(qu)^\beta] \frac{d_q h}{d_q u^\beta} + q \left\{ \frac{g[(qu)^\beta] - g(u^\beta)}{(qu)^\beta - qu^\beta} \right\} h(u^\beta).$$

3. $(u^\beta)^n : \mathbb{C} \rightarrow \mathbb{C}$ is q -differentiable at u^β and

$$\frac{d_q f}{d_q u^\beta} = \frac{q^{n\beta}(u^\beta)^n - q(u^\beta)^n}{(q^\beta u^\beta)^n - (qu^\beta)^n} [(q^\beta u^\beta)^{n-1} + (q^\beta u^\beta)^{n-2} qu^\beta + \dots + (qu^\beta)^{n-1}].$$

Proof. 1.

$$\begin{aligned} \frac{d_q f}{d_q u^\beta} &= \frac{g[(qu)^\beta] + h[(qu)^\beta] - qg(u^\beta) - qh(u^\beta)}{(qu)^\beta - qu^\beta} \\ &= \frac{g[(qu)^\beta] - qg(u^\beta)}{(qu)^\beta - qu^\beta} + \frac{h[(qu)^\beta] - qh(u^\beta)}{(qu)^\beta - qu^\beta} \\ &= \frac{d_q g}{d_q u^\beta} + \frac{d_q h}{d_q u^\beta} \end{aligned}$$

2.

$$\begin{aligned}
\frac{d_q f}{d_q u^\beta} &= \frac{g[(qu)^\beta]h[(qu)^\beta] - qg(u^\beta)h(u^\beta)}{(qu)^\beta - qu^\beta} \\
&= \frac{g[(qu)^\beta]h[(qu)^\beta] + qg[(qu)^\beta]h(u^\beta) - qg[(qu)^\beta]h(u^\beta) - qg(u^\beta)h(u^\beta)}{(qu)^\beta - qu^\beta} \\
&= g[(qu)^\beta] \left\{ \frac{h[(qu)^\beta] - qh(u^\beta)}{(qu)^\beta - qu^\beta} \right\} + q \left\{ \frac{g[(qu)^\beta] - g(u^\beta)}{(qu)^\beta - qu^\beta} \right\} \\
&= g[(qu)^\beta] \frac{d_q h}{d_q u^\beta} + q \left\{ \frac{g[(qu)^\beta] - g(u^\beta)}{(qu)^\beta - qu^\beta} \right\}
\end{aligned}$$

3.

$$\frac{d_q f}{d_q u^\beta} = \frac{(q^\beta u^\beta)^n - q(u^\beta)^n}{(qu)^\beta - qu^\beta},$$

multiplying by $\frac{(q^\beta u^\beta)^n - (qu)^\beta}{(q^\beta u^\beta)^n - (qu)^\beta}$,

$$\begin{aligned}
\frac{d_q f}{d_q u^\beta} &= \frac{(q^\beta u^\beta)^n - q(u^\beta)^n}{(qu)^\beta - qu^\beta} \cdot \frac{(q^\beta u^\beta)^n - (qu)^\beta}{(q^\beta u^\beta)^n - (qu)^\beta} \\
&= \frac{(q^\beta u^\beta)^n - q(u^\beta)^n}{(qu)^\beta - (qu)^\beta} \cdot \frac{(q^\beta u^\beta)^n - (qu)^\beta}{q^\beta u^\beta - qu^\beta} \\
&= \frac{(q^\beta u^\beta)^n - q(u^\beta)^n}{(qu)^\beta - (qu)^\beta} [(q^\beta u^\beta)^{n-1} + (q^\beta u^\beta)^{n-2} qu^\beta + \dots + (qu)^\beta] .
\end{aligned}$$

□

Remark 2.7. The proof for $f(v^\alpha)$ is similar.

Example 2.8. 1. For $f(u^\beta) = u^\beta$

$$\begin{aligned}
\frac{f[(qu)^\beta] - qf(u^\beta)}{(qu)^\beta - qu^\beta} &= \frac{(qu)^\beta - qu^\beta}{(qu)^\beta - qu^\beta} \\
&= 1.
\end{aligned}$$

2. If $f(v^\alpha) = u^\alpha$, then $\frac{d_q(u^\beta)}{d_q v^\alpha} = 0$.

3. $f(u^\beta) = (u^\beta)^3 + (v^\alpha)u^\beta$

$$\begin{aligned}
\frac{d_q f}{d_q u^\beta} &= \frac{[(qu)^\beta]^3 - q(u^\beta)^3}{(qu)^\beta - qu^\beta} + (v^\alpha) \frac{(qu)^\beta - qu^\beta}{(qu)^\beta - qu^\beta} \\
&= \frac{(q^\beta u^\beta)^3 - q(u^\beta)^3}{(qu)^\beta - (qu)^\beta} [(q^\beta u^\beta)^2 + q^{\beta+1} u^{\beta+1} + (qu)^\beta] + v^\alpha.
\end{aligned}$$

With these results, it is possible to define that q -spinor complex integral formula by the following theorem.

Theorem 2.9. Let Γ_q be the closed contour of the deformed quantum complex plane, and $u_0^\beta, v^\alpha \in \Gamma_q$ point spinors contained in the contour. The q -spinor complex integral formulas are defined by:

$$\oint_{\Gamma_q} \frac{f(u^\beta) d_q u^\beta}{(qu)^\beta - qu_0^\beta} = \frac{1}{q} \sum_{n=0}^{\infty} [(\bar{\sigma}_\mu^{-1})_{\dot{\alpha}\beta} f(u_0^\beta)]^n, \tag{44}$$

$$\oint_{\Gamma_q} \frac{f((qu)^\beta) d_q u^\beta}{(qu)^\beta - qu_0^\beta} = \sum_{n=0}^{\infty} [(\bar{\sigma}_\mu)_{\dot{\alpha}\beta} f((qu_0)^\beta)]^n, \tag{45}$$

$$\oint_{\Gamma_q} \frac{f(v^{\dot{\alpha}}) d_q v^{\dot{\alpha}}}{(qv)^{\dot{\alpha}} - qv_0^{\dot{\alpha}}} = \frac{1}{q} \sum_{m=0}^{\infty} [(\sigma_\mu^{-1})_{\alpha\dot{\beta}} f(v_0^{\dot{\alpha}})]^m, \tag{46}$$

$$\oint_{\Gamma_q} \frac{f((qv)^{\dot{\alpha}}) d_q v^{\dot{\alpha}}}{(qv)^{\dot{\alpha}} - qv_0^{\dot{\alpha}}} = \sum_{m=0}^{\infty} [(\sigma_\mu)_{\alpha\dot{\beta}} f((qv_0)^{\dot{\alpha}})]^m. \tag{47}$$

Proof. $d_q f$ is found from (38) and is integrated over closed contour Γ_q

$$\oint_{\Gamma_q} d_q f(u^\beta) = \oint_{\Gamma_q} \frac{f((qu)^\beta) d_q u^\beta}{(qu)^\beta - qu^\beta} - q \oint_{\Gamma_q} \frac{f(u^\beta) d_q u^\beta}{(qu)^\beta - qu^\beta}, \tag{48}$$

the left side of (48) may be equalated to

$$\sum_{n=0}^{\infty} [(\bar{\sigma}_\mu^{-1})_{\dot{\alpha}\beta} f(u^\beta)]^n, \text{ obtaining}$$

$$\sum_{n=0}^{\infty} [(\bar{\sigma}_\mu^{-1})_{\dot{\alpha}\beta}]^n [f(u^\beta)]^n = \oint_{\Gamma_q} \frac{f((qu)^\beta) d_q u^\beta}{(qu)^\beta - qu^\beta} - q \oint_{\Gamma_q} \frac{f(u^\beta) d_q u^\beta}{(qu)^\beta - qu^\beta}, \tag{49}$$

taking into account point spinors, then $[f(u^\beta)]^n = [f((qu_0)^\beta)]^n - [f(u_0^\beta)]^n$ is defined and, by substituting in (49), the following is obtained:

$$\sum_{n=0}^{\infty} [(\bar{\sigma}_\mu^{-1})_{\dot{\alpha}\beta}]^n [f((qu_0)^\beta)]^n - \sum_{n=0}^{\infty} [(\bar{\sigma}_\mu^{-1})_{\dot{\alpha}\beta}]^n [f(u_0^\beta)]^n = \oint_{\Gamma_q} \frac{f((qu)^\beta) d_q u^\beta}{(qu)^\beta - qu^\beta} - q \oint_{\Gamma_q} \frac{f(u^\beta) d_q u^\beta}{(qu)^\beta - qu^\beta}.$$

The expressions (44) and (45) are obtained by equalating terms that depend on $f((qu_0)^\beta)$ and $f(u_0^\beta)$. The same process is applied to get (46) and (47) from (39). \square

Example 2.10. Considering the following spinorial function $f(v^{i2}) = (v^{i2})^2$, and the point spinor $v_0^{i2} = qv^{i2}$ contained in the closed contour Γ_q . Applying (46) we have

$$\oint_{\Gamma_q} \frac{(v^{i2})^2 d_q v^{i2}}{(qv)^{i2} - qv^{i2}} = \frac{1}{q} \sum_{m=0}^{\infty} [(\bar{\sigma}_\mu^{-1})_{i\dot{1}}]^m (qv^{i2})^{2m},$$

taking in account the spinorial matrices defined in the Schmidt's work [6] (check Introduction) and if $\mu = -$, then

$$\begin{aligned} \oint_{\Gamma_q} \frac{(v^{i2})^2 d_q v^{i2}}{(qv)^{i2} - qv^{i2}} &= \frac{1}{q} \sum_{m=0}^{\infty} [(\bar{\sigma}_-^{-1})_{i1}]^m (qv^{i2})^{2m} \\ &= \frac{1}{q} \sum_{m=0}^{\infty} q^m (qv^{i2})^{2m} \\ &= \sum_{m=0}^{\infty} q^{3m-1} (v^{i2})^{2m}, \end{aligned}$$

and for the case $\mu = +$ the integral is zero.

3. q -Differential spinor equation

Based on the Pauli matrices presented in the works of Gori and Zettili [4],[7], 4×4 rotation matrices were defined in the following proposition.

Proposition 3.1. *The 4×4 rotation matrices can be expressed as follows:*

$$\hat{R}_x(\theta) = \begin{bmatrix} \cos(\theta/2) & i \sin(\theta/2) & 0 & 0 \\ i \sin(\theta/2) & \cos(\theta/2) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \quad \hat{R}_y(\theta) = \begin{bmatrix} 0 & \cos(\theta/2) & -\sin(\theta/2) & 0 \\ 0 & \sin(\theta/2) & \cos(\theta/2) & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix},$$

$$\hat{R}_z(\theta) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & e^{i\theta/2} & 0 & 0 \\ 0 & 0 & e^{-i\theta/2} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}. \quad (50)$$

With these rotation matrices, we can propose the following spinors, using as a starting point the definitions proposed by Beretetskii et al and Lachizee [3], [5].

Proposition 3.2. *The spinors ψ_α^β and φ_β^α can be expressed as follows:*

$$\psi_\alpha^\beta = \begin{bmatrix} \psi_\alpha \\ -\psi_\alpha \\ \psi_\beta \\ -\psi_\beta \end{bmatrix}, \quad \varphi_\beta^\alpha = \begin{bmatrix} \varphi_\alpha \\ -\varphi_\alpha \\ \varphi_\beta \\ -\varphi_\beta \end{bmatrix}, \quad (51)$$

and, when related to (50), spinorial components $\psi_x, \psi_y, \psi_z, \varphi_x, \varphi_y$ and φ_z are defined

$$\psi_x = \hat{R}_x(\theta)\psi_\alpha^\beta, \quad \psi_y = \hat{R}_y(\theta)\psi_\alpha^\beta, \quad \psi_z = \hat{R}_z(\theta)\psi_\alpha^\beta \quad (52)$$

$$\varphi_x = \hat{R}_x^\dagger(\theta)\varphi_\beta^\alpha, \quad \varphi_y = \hat{R}_y^\dagger(\theta)\varphi_\beta^\alpha, \quad \varphi_z = \hat{R}_z^\dagger(\theta)\varphi_\beta^\alpha, \quad (53)$$

and explicitly:

$$\psi_x = \begin{bmatrix} \psi_\alpha \cos(\theta/2) - i\psi_\alpha \sin(\theta/2) \\ i\psi_\alpha \sin(\theta/2) - \cos(\theta/2)\psi_\alpha \\ \psi_\beta \\ -\psi_\beta \end{bmatrix}, \quad \psi_y = \begin{bmatrix} -\psi_\alpha \cos(\theta/2) - \psi_\beta \sin(\theta/2) \\ -\psi_\alpha \sin(\theta/2) + \psi_\beta \cos(\theta/2) \\ \psi_\alpha \\ -\psi_\beta \end{bmatrix}, \quad \psi_z = \begin{bmatrix} \psi_\alpha \\ -\psi_\alpha e^{i\theta/2} \\ \psi_\beta e^{-i\theta/2} \\ -\psi_\beta \end{bmatrix}, \quad (54)$$

$$\varphi_x = \begin{bmatrix} \varphi_\alpha \cos(\theta/2) - i\varphi_\alpha \sin(\theta/2) \\ \varphi_\beta \\ -\varphi_\beta \end{bmatrix}, \quad \varphi_y = \begin{bmatrix} -\varphi_\alpha \cos(\theta/2) - \varphi_\beta \sin(\theta/2) \\ -\varphi_\alpha \sin(\theta/2) + \varphi_\beta \cos(\theta/2) \\ \varphi_\alpha \\ -\varphi_\beta \end{bmatrix}, \quad \varphi_z = \begin{bmatrix} \varphi_\alpha \\ -\varphi_\alpha e^{-i\theta/2} \\ \varphi_\beta e^{i\theta/2} \\ -\varphi_\beta \end{bmatrix}. \quad (55)$$

These expressions are conveyed as:

$$\psi_m = \hat{R}_m(\theta)\psi_\alpha^\beta, \quad \varphi_n = \hat{R}_n^\dagger(\theta)\varphi_\beta^\alpha, \quad m, n = x, y, z. \quad (56)$$

Remark 3.3. Beretetskii et al., define the bispinors as the pair $(\psi^\alpha, \varphi_\alpha)$, formulating the scalar product between bispinors [3]:

$$(\psi^\beta, \varphi_\beta) \cdot (\psi_\alpha, \varphi_\alpha) = \psi^\beta \psi_\alpha + \varphi_\beta \varphi_\alpha. \quad (57)$$

3.1. Spinorial partial differential equation

Definition 3.4. Let $\psi_\alpha^\beta, \psi_x, \psi_y, \psi_z, \psi_0^\beta$ be functions in \mathbb{C} , and a, b, f are also constants in \mathbb{C} . The partial spinor differential equation is given by:

$$a \left(\frac{\partial \psi_x}{\partial x} + \frac{\partial \psi_y}{\partial y} + \frac{\partial \psi_z}{\partial z} \right) + b \psi_0^\beta = f \psi_\alpha^\beta, \tag{58}$$

where ψ_x, ψ_y, ψ_z are defined in (54) and spinors $\psi_0^\beta, \psi_\alpha^\beta$ are expressed as

$$\psi_0^\beta = \begin{bmatrix} \psi_\alpha \\ -\psi_\alpha \\ -\psi^\beta \\ \psi^\beta \end{bmatrix}, \quad \psi_\alpha^\beta = \begin{bmatrix} \psi_\alpha \\ -\psi_\alpha \\ \psi^\beta \\ -\psi^\beta \end{bmatrix}, \tag{59}$$

and, similarly, for pointed components:

$$a \left(\frac{\partial \varphi_{\dot{x}}}{\partial x} + \frac{\partial \varphi_{\dot{y}}}{\partial y} + \frac{\partial \varphi_{\dot{z}}}{\partial z} \right) + b \varphi_0^{\dot{\alpha}} = f \varphi_{\dot{\beta}}^{\dot{\alpha}}, \tag{60}$$

and the spinors $\varphi_{\dot{x}}, \varphi_{\dot{y}}, \varphi_{\dot{z}}$ are given in (55) and $\varphi_0^{\dot{\alpha}}, \varphi_{\dot{\beta}}^{\dot{\alpha}}$ are expressed as:

$$\varphi_0^{\dot{\alpha}} = \begin{bmatrix} \varphi^{\dot{\alpha}} \\ -\varphi^{\dot{\alpha}} \\ -\varphi_{\dot{\beta}} \\ \varphi_{\dot{\beta}} \end{bmatrix}, \quad \varphi_{\dot{\beta}}^{\dot{\alpha}} = \begin{bmatrix} \varphi^{\dot{\alpha}} \\ -\varphi^{\dot{\alpha}} \\ \varphi_{\dot{\beta}} \\ -\varphi_{\dot{\beta}} \end{bmatrix}. \tag{61}$$

The following theorem shows the solutions of equations (58) and (60).

Theorem 3.5. For $\theta = \pi/2$, the solutions of equations (58) and (60) are given by:

$$\psi^\beta = u^{\alpha\beta} \exp \left[-\alpha x - \beta y + \left(\frac{f+b}{a} + \alpha + \beta \right) z \right], \tag{62}$$

$$\psi_\alpha = - \left\{ \left(\frac{f+b}{a\beta} \right) + \frac{\alpha}{\beta} + \frac{1}{\sqrt{2}} \left(\frac{f+b}{a} + \alpha + \beta \right) \right\} v_{\alpha\beta} \exp \left[-\alpha x - \beta y + \left(\frac{f+b}{a} + \alpha + \beta \right) z \right], \tag{63}$$

$$\varphi_{\dot{\beta}} = u_{\dot{\alpha}\dot{\beta}} \exp \left[-\dot{\alpha} x - \dot{\beta} y + \left(\frac{f+b}{a} + \dot{\alpha} + \dot{\beta} \right) z \right], \tag{64}$$

$$\varphi^{\dot{\alpha}} = \left\{ \left(\frac{f+b}{a\dot{\alpha}} \right) - \frac{\dot{\alpha}}{\dot{\beta}} + \frac{1}{\sqrt{2}\dot{\beta}} \left(\frac{f+b}{a} + \dot{\alpha} + \dot{\beta} \right) \right\} v^{\dot{\alpha}\dot{\beta}} \exp \left[-\dot{\alpha} x - \dot{\beta} y + \left(\frac{f+b}{a} + \dot{\alpha} + \dot{\beta} \right) z \right]. \tag{65}$$

Proof. Taking $\theta = \pi/2$ in (54), these spinors are obtained:

$$\psi_x = \begin{bmatrix} \psi_\alpha e^{-i\pi/4} \\ -\psi_\alpha e^{-i\pi/4} \\ \psi^\beta \\ -\psi^\beta \end{bmatrix}, \quad \psi_y = \begin{bmatrix} -\psi_\alpha \cos(\pi/4) - \psi^\beta \sin(\pi/4) \\ -\psi_\alpha \sin(\pi/4) + \psi^\beta \cos(\pi/4) \\ \psi_\alpha \\ -\psi^\beta \end{bmatrix}, \quad \psi_z = \begin{bmatrix} \psi_\alpha \\ -\psi_\alpha e^{i\pi/4} \\ \psi^\beta e^{-i\pi/4} \\ -\psi^\beta \end{bmatrix}$$

and, taking the real part, we find

$$\psi_x = \begin{bmatrix} \psi_\alpha \frac{1}{\sqrt{2}} \\ -\psi_\alpha \frac{1}{\sqrt{2}} \\ \psi^\beta \frac{1}{\sqrt{2}} \\ -\psi^\beta \end{bmatrix}, \quad \psi_y = \begin{bmatrix} (-\psi_\alpha - \psi^\beta) \frac{1}{\sqrt{2}} \\ (-\psi_\alpha + \psi^\beta) \frac{1}{\sqrt{2}} \\ \psi_\alpha \\ -\psi^\beta \end{bmatrix}, \quad \psi_z = \begin{bmatrix} \psi_\alpha \\ -\psi_\alpha \frac{1}{\sqrt{2}} \\ \psi^\beta \frac{1}{\sqrt{2}} \\ -\psi^\beta \end{bmatrix}, \tag{66}$$

and replacing (66) in (58), we obtain the following system of partial differential equations

$$\frac{a}{\sqrt{2}} \frac{\partial \psi_\alpha}{\partial x} - \frac{a}{\sqrt{2}} \frac{\partial \psi_\alpha}{\partial y} - \frac{a}{\sqrt{2}} \frac{\partial \psi^\beta}{\partial y} + a \frac{\partial \psi_\alpha}{\partial z} = (f - b)\psi_\alpha, \quad (67)$$

$$-\frac{a}{\sqrt{2}} \frac{\partial \psi_\alpha}{\partial x} - \frac{a}{\sqrt{2}} \frac{\partial \psi_\alpha}{\partial y} + \frac{a}{\sqrt{2}} \frac{\partial \psi^\beta}{\partial y} - \frac{a}{\sqrt{2}} \frac{\partial \psi_\alpha}{\partial z} = -(f - b)\psi_\alpha, \quad (68)$$

$$a \frac{\partial \psi^\beta}{\partial x} + a \frac{\partial \psi_\alpha}{\partial y} + \frac{a}{\sqrt{2}} \frac{\partial \psi^\beta}{\partial z} = (f + b)\psi^\beta, \quad (69)$$

$$a \frac{\partial \psi^\beta}{\partial x} + a \frac{\partial \psi^\beta}{\partial y} + a \frac{\partial \psi^\beta}{\partial z} = (f + b)\psi^\beta. \quad (70)$$

Applying the method to solve partial differential equations by separation of variables in (70); in other words, by defining $\psi^\beta = F(x)G(y)H(z)$, we obtain

$$\frac{1}{F(x)} \frac{dF(x)}{dx} + \frac{1}{G(y)} \frac{dG(y)}{dy} + \frac{1}{H(z)} \frac{dH(z)}{dz} = \frac{f + b}{a}, \quad (71)$$

equating each component to the separation constants α, β :

$$\frac{1}{F(x)} \frac{dF(x)}{dx} = -\alpha, \quad F(x) \simeq A_\alpha e^{-\alpha x}, \quad (72)$$

$$\frac{1}{G(y)} \frac{dG(y)}{dy} = -\beta, \quad G(y) \simeq B_\beta e^{-\beta y}, \quad (73)$$

$$\frac{1}{H(z)} \frac{dH(z)}{dz} = \frac{f + b}{a} + \alpha + \beta, \quad (74)$$

$$H(z) = D_{\alpha\beta} \exp \left[\alpha x + \beta y + \left(\frac{f + b}{a} + \alpha + \beta \right) z \right]. \quad (75)$$

Therefore, the solution is given by

$$\psi^\beta = (A_\alpha e^{-\alpha x}) \cdot (B_\beta e^{-\beta y}) \cdot D_{\alpha\beta} \exp \left[\left(\frac{f + b}{a} + \alpha + \beta \right) z \right], \quad (76)$$

$$\psi^\beta = u^{\alpha\beta} \exp \left[\alpha x + \beta y + \left(\frac{f + b}{a} + \alpha + \beta \right) z \right]. \quad (77)$$

To find ψ_α , (77) is replaced in (69), resulting in

$$\begin{aligned} \frac{\partial \psi_\alpha}{\partial y} &= \left(\frac{f + b}{a} \right) u_{\alpha\beta} \exp \left[\alpha x + \beta y + \left(\frac{f + b}{a} + \alpha + \beta \right) z \right] \\ &\quad + \alpha \exp \left[\alpha x + \beta y + \left(\frac{f + b}{a} + \alpha + \beta \right) z \right] \\ &\quad - \frac{1}{\sqrt{2}} \left(\frac{f + b}{a} + \alpha + \beta \right) \exp \left[\alpha x + \beta y + \left(\frac{f + b}{a} + \alpha + \beta \right) z \right]. \end{aligned} \quad (78)$$

On the other hand, for the pointed spinors described by eq. (60), the same angle $\theta = \pi/2$ is used in (55), resulting in the following system of differential equations:

$$\frac{a}{\sqrt{2}} \frac{\partial \varphi^{\dot{\alpha}}}{\partial x} - \frac{a}{\sqrt{2}} \frac{\partial \varphi^{\dot{\alpha}}}{\partial y} - \frac{a}{\sqrt{2}} \frac{\partial \varphi_{\dot{\beta}}}{\partial y} + a \frac{\partial \varphi^{\dot{\alpha}}}{\partial z} = (f - b)\varphi^{\dot{\alpha}}, \tag{79}$$

$$-\frac{a}{\sqrt{2}} \frac{\partial \varphi^{\dot{\alpha}}}{\partial x} + \frac{a}{\sqrt{2}} \frac{\partial \varphi_{\dot{\beta}}}{\partial y} - \frac{a}{\sqrt{2}} \frac{\partial \varphi^{\dot{\alpha}}}{\partial y} - \frac{a}{\sqrt{2}} \frac{\partial \varphi^{\dot{\alpha}}}{\partial z} = -(f - b)\varphi^{\dot{\alpha}}, \tag{80}$$

$$a \frac{\partial \varphi_{\dot{\beta}}}{\partial x} + a \frac{\partial \varphi^{\dot{\alpha}}}{\partial y} + \frac{a}{\sqrt{2}} \frac{\partial \varphi_{\dot{\beta}}}{\partial z} = (f + b)\varphi_{\dot{\beta}}, \tag{81}$$

$$a \frac{\partial \varphi_{\dot{\beta}}}{\partial x} + a \frac{\partial \varphi_{\dot{\beta}}}{\partial y} + a \frac{\partial \varphi_{\dot{\beta}}}{\partial z} = (f + b)\varphi_{\dot{\beta}}, \tag{82}$$

and, by solving equation (82) in the same way as it was done in (70) and defining $\varphi_{\dot{\beta}}$ as the product of functions $M(x)N(y)P(z)$, the following expressions analogous to (72 - 75) are obtained:

$$\frac{1}{M(x)} \frac{dM(x)}{dx} = -\dot{\alpha}, \quad M(x) = K_{\dot{\alpha}} e^{-\dot{\alpha}x}, \tag{83}$$

$$\frac{1}{N(y)} \frac{dN(y)}{dy} = -\dot{\beta}, \quad N(y) = L_{\dot{\beta}} e^{-\dot{\beta}y}, \tag{84}$$

$$\frac{1}{P(z)} \frac{dP(z)}{dz} = \frac{f + b}{a} + \dot{\alpha} + \dot{\beta}, \tag{85}$$

$$P(z) = E_{\dot{\alpha}\dot{\beta}} \exp \left[\left(\frac{f + b}{a} + \dot{\alpha} + \dot{\beta} \right) z \right], \tag{86}$$

and substituting the solutions for $M(x), N(y)$ and $P(z)$ into the product $M(x)N(y)P(z)$, we have

$$\varphi_{\dot{\beta}} = (K_{\dot{\alpha}} e^{-\dot{\alpha}x}) \cdot (L_{\dot{\beta}} e^{-\dot{\beta}y}) \cdot E_{\dot{\alpha}\dot{\beta}} \exp \left[\left(\frac{f + b}{a} + \dot{\alpha} + \dot{\beta} \right) z \right] \tag{87}$$

$$\varphi_{\dot{\beta}} = u_{\dot{\alpha}\dot{\beta}} \exp \left[-\dot{\alpha}x - \dot{\beta}y + \left(\frac{f + b}{a} + \dot{\alpha} + \dot{\beta} \right) z \right], \tag{88}$$

which corresponds to (64). Now, to obtain $\varphi^{\dot{\alpha}}$, the previous solution is substituted in (80), multiplied by dy , and finally, integrated both sides to obtain (65). Regarding the terms $u^{\alpha\beta}, v_{\alpha\beta}, u_{\dot{\alpha}\dot{\beta}}, v^{\dot{\alpha}\dot{\beta}}$, these are the coefficients of the previously mentioned solutions. \square

3.2. The lorentzian q -spinor differential equations

Definition 3.6. We consider the q -Lorentzian spinor variables $x^\beta, y^{\dot{\alpha}} \in \mathbb{C}$, and a function $f : \mathbb{C} \rightarrow \mathbb{C}$. The q -Lorentzian differential equations are defined as:

$$\frac{d_q f(x^\beta)}{d_q y^{\dot{\alpha}}} = \frac{\Psi(y^{\dot{\alpha}})}{y^{\dot{\alpha}} - x^\beta}, \tag{89}$$

$$\frac{d_q f(y^{\dot{\alpha}})}{d_q x^\beta} = \frac{\Phi(x^\beta)}{x^\beta - y^{\dot{\alpha}}}. \tag{90}$$

Lemma 3.7. The solutions of (89) and (90) over the contour Γ_q can be written as

$$f(x^\beta) = \frac{1}{q} \sum_{m=0}^{\infty} [(\sigma_\mu^{-1})_{\dot{\alpha}\dot{\beta}} \Psi(y^{\dot{\alpha}})]^m, \tag{91}$$

$$f(y^{\dot{\alpha}}) = \frac{1}{q} \sum_{m=0}^{\infty} [(\bar{\sigma}_\mu^{-1})_{\dot{\alpha}\dot{\beta}} \Phi(x^\beta)]^m. \tag{92}$$

Proof. In order to solve (89), it is sufficient to use (46), resulting:

$$\frac{d_q f(x^\beta)}{d_q y^{\dot{\alpha}}} = \frac{\Psi(y^{\dot{\alpha}})}{y^{\dot{\alpha}} - x^\beta},$$

integrating both sides over the contour Γ_q

$$\begin{aligned} \oint_{\Gamma_q} d_q f(x^\beta) &= \oint_{\Gamma_q} \frac{\Psi(y^{\dot{\alpha}}) d_q y^{\dot{\alpha}}}{y^{\dot{\alpha}} - x^\beta}, \\ f(x^\beta) &= \oint_{\Gamma_q} \frac{\Psi(y^{\dot{\alpha}}) d_q y^{\dot{\alpha}}}{y^{\dot{\alpha}} - x^\beta} \end{aligned}$$

taking into account (46) finally

$$f(x^\beta) = \frac{1}{q} \sum_{m=0}^{\infty} [(\sigma_\mu^{-1})_{\alpha\dot{\beta}} \Psi(x^\beta)]^m.$$

The same process is applied to get (92) from (90). \square

4. Comments

In section 3, a combination of the q -Lorentzian algebra formalism and the deformed complex variable is proposed based on section 2, though the latter is not explicit in the literature. Nevertheless, its development can be totally formulated from its derivatives mentioned in expressions (38) and (39), and its spinor contour integral q -forms, described by (44) - (47). These last expressions contain deformed spin matrices $(\sigma_\mu)_{\alpha\dot{\beta}}, (\sigma_\mu^{-1})_{\dot{\alpha}\beta}$ defined in Schmidt work [6]. It should be emphasized, that in this case, these matrices are formulated in the Minkowski space and that they are also spin-boson matrices. Hopefully, in future works, the spinor complex q -variable formulation can be achieved, but for the fermionic part. In section 3, a spinor partial differential equation (given by (58)) was proposed, and its solutions are given by theorem 4. Its solutions were obtained using angle $\theta = \pi/2$. Clearly, (77) and (87) are not unique, which means that, when the rotation angle varies, other solutions are obtained; consequently, other spinor deformed algebras are obtained. For future works on this matter, it is possible to propose the formalism of a general expression of the spinor partial differential equation. Using this formalism, it is possible to formulate another kind of relativistic wave equation as spinor representation substituting $a = -i\hbar c, b = mc^2$ y $f = E$, obtaining

$$-i\hbar c \left(\frac{\partial \psi_x}{\partial x} + \frac{\partial \psi_y}{\partial y} + \frac{\partial \psi_z}{\partial z} \right) + mc^2 \psi_0^\beta = E \psi_\alpha^\beta, \quad (93)$$

and its interpretation in their solutions. It is important to consider that this formulation was done without deformation. Other suggestion for further work, is the problem of describing the q -relativistic wave equation

$$i\partial_k^q \psi_q^k + m\psi = E\psi_0, \quad k = 1, 2, 3. \quad (94)$$

for some Minkowskian-valued spinors

$$\psi_q^+ = \begin{bmatrix} 0 \\ kq^{1/2} \lambda_+ \varphi_{\dot{\beta}} \end{bmatrix}, \psi_q^- = \begin{bmatrix} kq^{1/2} \lambda_+ \psi^\alpha \\ 0 \end{bmatrix}, \psi_q^3 = \begin{bmatrix} kq \varphi_{\dot{\beta}} \\ k \psi^\alpha \end{bmatrix}, \psi_0 = \begin{bmatrix} -kq^{-1} \varphi_{\dot{\beta}} \\ k \psi^\alpha \end{bmatrix} \text{ and } \psi = \begin{bmatrix} \psi^\alpha \\ \varphi_{\dot{\beta}} \end{bmatrix},$$

and is subject to Pauli matrices in the Minkowskian space proposed in [1].

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